

RIVER TRASH DETECTION ON DATABRICKS WITH

THE OCEAN CLEANUP

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1 - Background

Your Presenters



- Data science background
- ~2 years at Databricks
- Studied environmental science
- Passionate about the oceans



- Data engineering background
- ~1 years at Databricks
- Studied math & computer science
- Passionate about the environment

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Databricks for Good

Volunteer Databricks Initiative



databricks

- 3 verticals
 - Education
 - Foreign Aid
 - Environment
- Pro-bono
- Databricks employees working nights/weekends

- 1. Scoping
- 2. Projects
- 3. Marketing fluff

- 1. Scoping
 - a. Reliability + stability of pipelines
- 2. Projects
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2. Projects

- a. Architecture review and setup
- b. RMS Pipeline
- c. Ingestion framework template
- 3. Marketing fluff

- 1. Scoping
 - a. Reliability + stability of pipelines
- 2. Projects
 - a. Architecture review and setup
 - b. RMS Pipeline
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- 3. Marketing fluff
 - a. Blog post
 - b. Data + Al Summit Talk
 - c. Award?

2 - The Ocean Cleanup

SENSORS CAPTURE DATA FROM RIVERS

River Monitoring Systems

•Mounted cameras

- >50% river width
- 2-3 images / 15 min
- •Water level sensors



RMS IS STRATEGICALLY DEPLOYED

Goal: Global coverage



Current Footprint

- •12 RMS deployments
- •62 cameras installations
- •130K images/week

IMAGES AND METADATA ARE INGESTED



COMPUTER VISION TO TRACK TRASH

Weekly, per-camera pipelines process images



Operational + deployment metadata

Postgres Database

MIGRATING TO DATABRICKS

BRIDGING THE GAPS

Main objective: Migrate to Databricks



Incremental

- Exactly once
- Reduce cost
- Increase efficiency
- Custom state management solution



Dynamically Distributed

- Parallelize existing Pandas code
- Increase efficiency
- Reduce complexity

INCREMENTAL

DESIRED PIPELINE BEHAVIOR

Process images exactly once by default, but support:

Process images for a subset of cameras

Reprocess images





INCREMENTAL METADATA INGESTION

Using Auto Loader and Change Data Feed (CDF)



Incrementally ingest all new images using Auto Loader

INCREMENTAL METADATA INGESTION

Using Auto Loader and Change Data Feed (CDF)

P.	YTHON				
(:	(spark				
	.readStream				
	.format("cloudFiles")				
	.option("cloudFiles.format", "binaryFile")				
	.option('pathGlobFilter', '*.jpg')				
	.option("recursiveFileLookup", "true")				
	.load(f"wasbs://{container}@{storage_account}.blob.core.windows.net/{image_path}")				
	.drop("content", "length")				
	.withColumn("camera_serial", regexp_extract("path", "^.*?/.*?/.*?/.*?/(.*?)/", 1))				
	.writeStream				
	.option("checkpointLocation", checkpoint_path)				
	.trigger(availableNow=True)				
	.toTable(image_metadata_path)				
)					

METADATA-DRIVEN FILTERING

With custom state management



METADATA-DRIVEN FILTERING

With custom state management

PYTHON
<pre>filter_conds = [(col("camera_serial") == camera_serial) & (col("_commit_version") > (0 if reprocess else data.get(camera_serial, 0))) for camera_serial in camera_serials]</pre>
<pre>image_metadata_df = (spark .read .format("delta") .option("readChangeFeed", "true") .option("startingVersion", 0) .table(bronze_image_table_path) .filter(reduce(lambda x, y: x y, filter_conds)))</pre>

METADATA READY TO DRIVE PROCESSING

	${\bf A}^{\rm B}_{\rm C}$ path	C modificationTime	${\tt A}^{\rm B}_{\rm C}$ camera_serial	^B _c image_name	🗟 date
1	> wasbs://attachments	2024-04-12T08:22:42.000	PTM5165	rms_mella_4_ptm5165_20240301T1100_1.jpg	2024-03-01
2	> wasbs://attachments	2024-04-12T08:22:47.000	PTM5165	rms_mella_4_ptm5165_20240301T1100_2.jpg	2024-03-01
3	> wasbs://attachments	2024-04-12T08:22:49.000	PTM5165	rms_mella_4_ptm5165_20240307T1720_1.jpg	2024-03-07
4	> wasbs://attachments	2024-04-12T08:22:49.000	PTM5165	rms_mella_4_ptm5165_20240305T1450_2.jpg	2024-03-05
5	> wasbs://attachments	2024-04-12T08:22:38.000	PTM5165	rms_mella_4_ptm5165_20240305T1450_1.jpg	2024-03-05
6	> wasbs://attachments	2024-04-12T08:22:35.000	PTM5165	rms_mella_4_ptm5165_20240302T1640_2.jpg	2024-03-02
7	> wasbs://attachments	2024-04-12T08:22:41.000	PTM5165	rms_mella_4_ptm5165_20240303T1740_1.jpg	2024-03-03

DYNAMICALLY DISTRIBUTED

WE CONSIDERED THREE OPTIONS

Ray on Spark

- Distributed framework
- Logical partitioning
- Parallelize over nay iterable
- GA on Databricks
- Overhead
- Lack of familiarity

Pandas UDFs

- Native Spark
- Vectorized Spark-> Pandas transformations via Apache Arrow
- Apply Python function to PySpark columns, DataFrames
- GROUPED_MAP supports Pandas DataFrame -> Pandas DataFrame on grouped data

Pandas function APIs

- Native Spark
- Vectorized Spark-> Pandas transformations via Apache Arrow
- Apply Python function to PySpark DataFrames
- .applyInPandas() supports
 Pandas DataFrame -> Pandas
 DataFrame on grouped data
- Higher-level API

INCREMENTAL METADATA INGESTION

Using Auto Loader and Change Data Feed (CDF)

PYTHON				
<pre>def apply_pipeline(key, pdf): filtered_images = image_filtering(pdf) inference_results = batch_inference(filtered_images) tracks = object_tracking(inference_results) flow_speed = calculate_flow_speed(tracks) object_area = calculate_object_area(flow_speed) return vector_filtering(object_area)</pre>				
<pre>results = (image_metadata_df .groupBy("camera_serial", "date") .applyInPandas(apply_pipeline, schema))</pre>				

END TO END ARCHITECTURE



3 - Results

Outcomes

Open source highly-parallelizable ETL

- 1. Consolidated tooling
- 2. Incremental processing
- 3. Databricks stack

Camera Monitoring Dashboard (KPI)

DBSQL Legacy Dashboard



Total Plastic Detections (KPI)

DBSQL Dashboard + GenAl Assistant

Sum of Daily Number of Inference per Deployment



Water Level (Descriptive Stats)

DBSQL Dashboard + GenAl Assistant

Median Water Height per Deployment



Water Level (Outlier Detection)

DBSQL Dashboard + GenAl Assistant

Outlier Water Level Readings per Camera



Next Steps

Let the Databricks product speak for itself.

Opportunities

- Unification of tooling
- Power
- UC

Challenges

- Designing organizational policies for scaling
- Migration
- Employee education

Thank You!

